



Part-turn gearboxes GS 50.3 – GS 250.3



Operation instructions

Assembly, commissioning

Read operation instructions first.

- Observe safety instructions.
- These operation instructions are part of the product.
- Retain operation instructions during product life.
- Pass on instructions to any subsequent user or owner of the product.

Purpose of the document:

This document contains information for installation, commissioning, operation and maintenance staff. It is intended to support device installation and commissioning.

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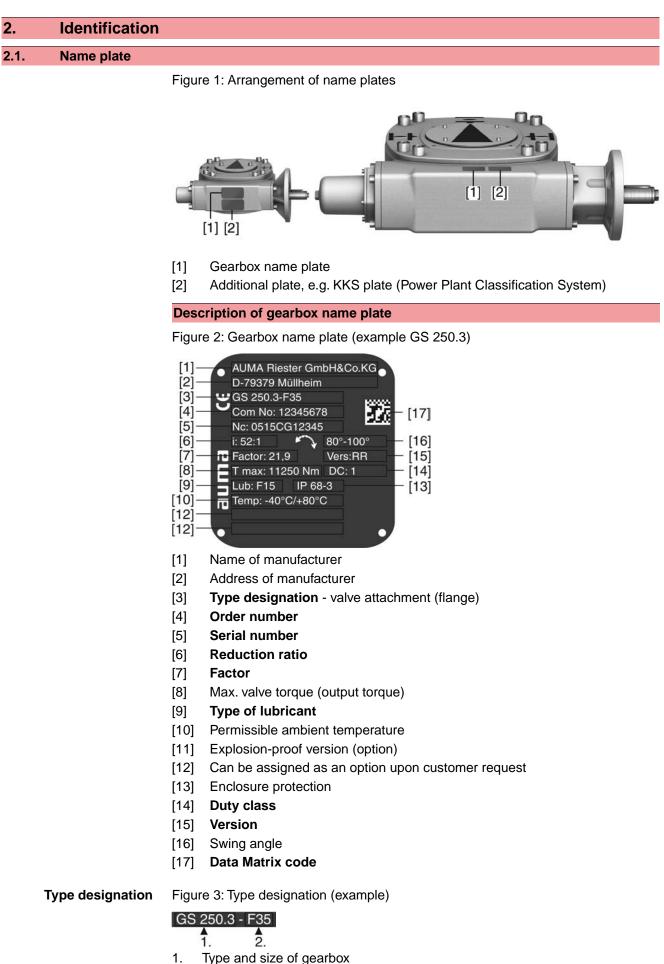
1. Safety instruc	ctions				
1.1. Basic information	on on safety				
Standards/directives	Our products are designed and manufactured in compliance with recognised standards and directives. This is certified in a Declaration of Incorporation and an EC Declaration of Conformity.				
	The end user or the contractor must ensure that all legal requirements, directives, guidelines, national regulations and recommendations with respect to assembly, electrical connection, commissioning and operation are met at the place of installation.				
Safety instructions/warn- ings	All personnel working with this device must be familiar with the safety and warning instructions in this manual and observe the instructions given. Safety instructions and warning signs on the device must be observed to avoid personal injury or property damage.				
Qualification of staff	Assembly, electrical connection, commissioning, operation, and maintenance must be carried out exclusively by suitably qualified personnel having been authorised by the end user or contractor of the plant only.				
	Prior to working on this product, the staff must have thoroughly read and understood these instructions and, furthermore, know and observe officially recognised rules regarding occupational health and safety.				
	Work performed in potentially explosive atmospheres is subject to special regulations which have to be observed. The end user or contractor of the plant are responsible for respect and control of these regulations, standards, and laws.				
Commissioning	Prior to commissioning, it is important to check that all settings meet the requirements of the application. Incorrect settings might present a danger to the application, e.g. cause damage to the valve or the installation. The manufacturer will not be held liable for any consequential damage. Such risk lies entirely with the user.				
Operation	Prerequisites for safe and smooth operation:				
	Correct transport, proper storage, mounting and installation, as well as careful commissioning.				
	Only operate the device if it is in perfect condition while observing these instruc- tions.				
	• Immediately report any faults and damage and allow for corrective measures.				
	Observe recognised rules for occupational health and safety.				
	Observe the national regulations.				
	 During operation, the device warms up and increased surface temperature may occur. To prevent possible burns, we recommend checking the surface temper- ature using an appropriate thermometer and wearing protective gloves, if re- quired, prior to working on the device. 				
Protective measures	The end user or the contractor are responsible for implementing required protective measures on site, such as enclosures, barriers, or personal protective equipment for the staff.				
Maintenance	To ensure safe device operation, the maintenance instructions included in this manual must be observed.				
	Any device modification requires prior consent of the manufacturer.				
1.2. Range of application	ation				
	AUMA part-turn gearboxes are designed for the operation of industrial valves, e.g. butterfly valves, ball valves and dampers.				
	Other applications require explicit (written) confirmation by the manufacturer.				
	The following applications are not permitted, e.g.:				

Industrial trucks according to EN ISO 3691

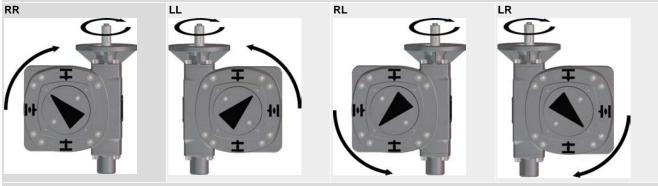
		Lifting appliances according to EN 14502
		Passenger lifts according to DIN 15306 and 15309 Service lifts according to EN 81 1/41
		 Service lifts according to EN 81-1/A1 Escalators
		Continuous duty
		 Potentially explosive atmospheres in combination with F21 lubricant type (refer to name plate)
		Radiation exposed areas in nuclear power plants
		No liability can be assumed for inappropriate or unintended use.
		Observance of these operation instructions is considered as part of the device's designated use.
1.3.	Warnings and no	otes
		The following warnings draw special attention to safety-relevant procedures in these operation instructions, each marked by the appropriate signal word (DANGER, WARNING, CAUTION, NOTICE).
		Indicates an imminently hazardous situation with a high level of risk. Failure to observe this warning could result in death or serious injury.
		Indicates a potentially hazardous situation with a medium level of risk. Failure to observe this warning could result in death or serious injury.
		Indicates a potentially hazardous situation with a low level of risk. Failure to observe this warning may result in minor or moderate injury. May also be used with property damage.
	NOTICE	Potentially hazardous situation. Failure to observe this warning may result in property damage. Is not used for personal injury.
	NOTICE	
	NOTICE	property damage. Is not used for personal injury.
		property damage. Is not used for personal injury. Arrangement and typographic structure of the warnings Type of hazard and respective source! Potential consequence(s) in case of non-observance (option) → Measures to avoid the danger
1.4.		property damage. Is not used for personal injury. Arrangement and typographic structure of the warnings Type of hazard and respective source! Potential consequence(s) in case of non-observance (option) → Measures to avoid the danger → Further measure(s) Safety alert symbol
1.4.	Anger Danger	property damage. Is not used for personal injury. Arrangement and typographic structure of the warnings Type of hazard and respective source! Potential consequence(s) in case of non-observance (option) → Measures to avoid the danger → Further measure(s) Safety alert symbol
1.4.	Anger Danger	property damage. Is not used for personal injury. Arrangement and typographic structure of the warnings Type of hazard and respective source! Potential consequence(s) in case of non-observance (option) → Measures to avoid the danger → Further measure(s) Safety alert symbol
1.4.	DANGER References and	property damage. Is not used for personal injury. Arrangement and typographic structure of the warnings Type of hazard and respective source! Potential consequence(s) in case of non-observance (option) → Measures to avoid the danger → Further measure(s) Safety alert symbol A warns of a potential personal injury hazard. The signal word (here: DANGER) indicates the level of hazard. symbols The following references and symbols are used in these instructions:

<> Reference to other sections

Terms in brackets shown above refer to other sections of the document which provide further information on this topic. These terms are either listed in the index, a heading or in the table of contents and may quickly be found.



	2. Flange size for valve attachment								
	Type and size								
	These instructions apply to the following device types and sizes:								
Part-turn actuators type GS , sizes 50.3 – 250.3									
Order number	The product can be identified using this number and the technical data as well as order-related data pertaining to the device can be requested.								
	Please always state this number for any product inquiries.								
On the Internet at http://www.auma.com , we offer a service allowing author users to download order-related documents such as wiring diagrams and tec data (both in German and English), inspection certificates and the operation instructions when entering the order number.									
Serial number	Description of the particl number (with the supermule of 05420042245)								
	Description of the serial number (with the example of 0512CG12345) 05 15 CG12345								
	05 Positions 1 + 2 : Assembly in week = week 05								
	15 Positions 3 + 4 : Year of manufacture = 2015								
	CG12345 Internal number for unambiguous product identification								
Reduction ratio	The reduction ratio within gearing and primary reduction gearing reduces the required input torques and increases the operating time.								
Factor	Mechanical conversion factor for actuator size determination:								
	Input torque = required valve torque (output torque)/factor								
Type of lubricant	AUMA abbreviation for type of lubricant used in the gear housing.								
	Danger of explosion when using inappropriate lubricant in potentially explosive atmospheres! \rightarrow Do not use gearboxes with F21 lubricant in potentially explosive atmospheres.								
	\rightarrow Do not mix different lubricants.								
Duty class	Hass The duty class specifies the application range of a gearbox relating to the lifetime requirements. The duty class is only specified for gearboxes in operation mode class A (OPEN-CLOSE duty).								
	 Duty class 1: suitable for motor operation, meets the lifetime requirements of EN 15714-2 								
	 Duty class 2: suitable for motor operation of rarely or infrequently operated valves which do not exceed 1,000 operations across their total lifetime. 								
	 Duty class 3: suitable (exclusively) for manual operation with approximately 250 operations, in compliance with the specified lifetime requirements in EN 1074-2. 								
	Please refer to separate Technical data for further information on duty classes.								
Version	The first letter of the version indicates the position of the worm shaft in relation to the worm wheel (view on input shaft).								
	The second letter indicates the direction of rotation at the output drive (view on housing cover) for clockwise rotation at the input shaft.								



Versions: Worm shaft position and direction of rotation of output drive GS 50.3 - GS 250.3

Description of the four different versions (view on housing cover):

Initials	Direction of rotation at input shaft	Position of worm shaft	Direction of rotation at output drive
RR	Clockwise	Right	Clockwise
LL	Clockwise	Left	Counterclockwise
RL	Clockwise	Right	Counterclockwise
LR	Clockwise	Left	Clockwise

Data Matrix code

When registered as authorised user, you may use the **AUMA Support App** to scan the Data Matrix code and directly access the order-related product documents without having to enter order number of serial number.

Figure 4: Link to the App store:



2.2. Short description

AUMA worm gearboxes are part-turn gearboxes converting a rotary movement at the input shaft into a part-turn movement at the output drive. The worm gearboxes are driven either via electric motor (by means of a multi-turn actuator) or manually (e.g. via a handwheel). The required input torques are reduced due to high reduction ratios. In standard version, internal end stops limit the swing angle to 100°.

Worm gearboxes are available in different versions to implement various mounting conditions and rotary directions.

3. Transport, storage and packaging 3.1. Transport For transport to place of installation, use sturdy packaging. Hovering load! DANGER Risk of death or serious injury. \rightarrow Do NOT stand below hovering load. → Attach ropes or hooks for the purpose of lifting by hoist only to housing and NOT to handwheel. \rightarrow Check eyebolts for tight seat in housing (verify reach of the screws). \rightarrow Observe manufacturer specifications for fixing lifting straps and roundslings. \rightarrow Respect total weight of combination (gearbox, primary reduction gearing, actuator). Table 1: Weights including grease filling in gear housing Version with base and lever Туре Standard version [kg]¹⁾ [kg] 7 10 GS 50.3 GS 63.3 12 23 GS 80.3 16 29 GS 100.3 (52:1/107:1) 33 58 GS 100.3 (126:1/160:1/208:1) 39 64 GS 125.3 (52:1) 40 89 GS 125.3 (126:1/160:1/208:1) 46 95 GS 160.3 (54:1) 80 139 GS 160.3 (218:1/442:1/880:1) 91 150 GS 200.3 (53:1) 258 140 GS 200.3 (214:1/434:1) 160 278 GS 200.3 (864:1/1 752:1) 170 288 GS 250.3 (52:1) 273 467 GS 250.3 (210:1/411:1) 296 490 502 GS 250.3 (848:1/1 718:1) 308 Additional weights when mounting extension flanges F30 for GS 125.3 18 F35 for GS 160.3 33 F40 for GS 200.3 48 F48 for GS 250.3 75 Specified weight includes unmachined coupling 1)

3.2. Storage

NOTICE

Danger of corrosion due to inappropriate storage!

- \rightarrow Store in a well-ventilated, dry room (maximum humidity 70 %).
- \rightarrow Protect against floor dampness by storage on a shelf or on a wooden pallet.
- \rightarrow Cover to protect against dust and dirt.
- \rightarrow Apply suitable corrosion protection agent to uncoated surfaces.

Long-term storage If the device must be stored for a long period (more than 6 months), the following points must be observed in addition:

 Prior to storage: Protect uncoated surfaces, in particular the output drive parts and mounting surface, with long-term corrosion protection agent. 2.

At an interval of approx. 6 months: Check for corrosion. If first signs of corrosion show, apply new corrosion protec-tion.

3.3.	Packaging	
		Our products are protected by special packaging for transport when leaving the factory. The packaging consists of environmentally friendly materials which can easily be separated and recycled. We use the following packaging materials: wood, cardboard, paper, and PE foil. For the disposal of the packaging material, we recommend recycling and collection centres.

4. Assembly

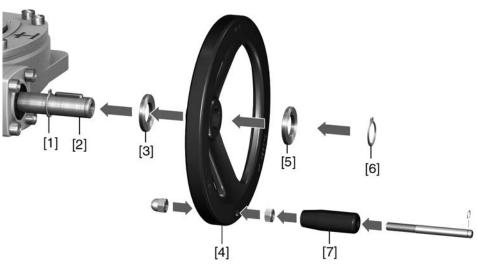
4.1. Mounting position

The gearboxes described here can be operated without restriction in any mounting position.

4.2. Handwheel fitting

Gearboxes designed for manual operation are supplied with a separate handwheel. Fitting is performed on site according to the description below.

Figure 5: Handwheel



- [1] Retaining ring for input shaft (partly required)
- [2] Gear input shaft
- [3] Spacer (partly required)
- [4] Handwheel
- [5] Spacer (partly required)
- [6] Retaining ring
- [7] Ball handle

1. For input shafts with keyway: Place retaining ring [1] onto input shaft [2].

- 2. If required, fit spacer [3].
- 3. Slip handwheel [4] onto input shaft.
- 4. If required, fit spacer [5].
- 5. Secure handwheel [4] using the retaining ring [6] supplied.
- 6. Fit ball handle [7] to handwheel.

4.3. Multi-turn actuators for motor operation

Refer to the operation instructions pertaining to the multi-turn actuator for indications on how to mount multi-turn actuators to gearboxes.

This chapter supplies basic information and instructions which should be considered in addition to the operation instructions of the multi-turn actuator.

Screws to actuator

Screws are included in the scope of delivery of the gearbox for mounting AUMA multi-turn actuators. When mounting other actuators, the screws might be either too long or too short (insufficient reach of screws).

🗥 WARNING

Risk of actuator falling off in case inappropriate screws used should shear.

Risk of death or serious injury!

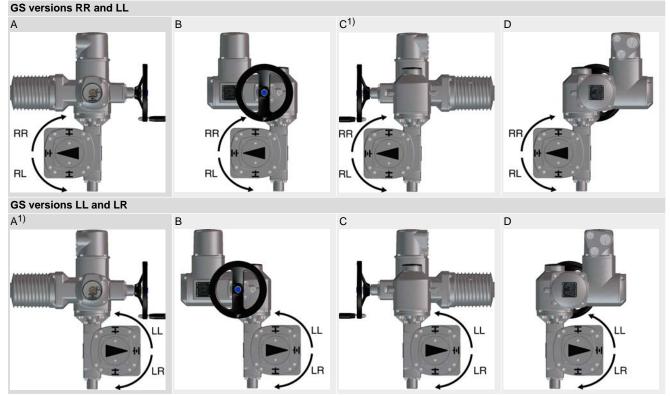
- \rightarrow Check length of screws.
- \rightarrow Only use screws with strength class specified herein.

The reach of screws must be sufficient for the internal threads to ensure the supporting strength of the device and to accept the lateral forces due to the applied torque.

Screws which are too long could make contact with the housing parts, presenting the risk that the device performs a radial shift with respect to the gearbox. This can lead to shearing of the screws.

4.3.1. Mounting positions Multi-turn actuators with part-turn gearboxes

Mounting positions A – D for multi-turn actuators with part-turn gearboxes



 Caution: For multi-turn actuators SA/SAR 14.2 and 14.6 with GS 125.3, mounting position C is not possible for RR and RL versions; mounting position A is not possible for LL and LR versions.

Please consider possible space constraints on site when selecting the mounting position.

Mounting positions may easily be changed at a later date.

Up to size GS 125.3, the multi-turn actuator-gearbox combination is delivered in the ordered mounting position. For packing reasons, actuator and gearbox will be delivered separately from size GS 160.3.

4.3.2. Input mounting flange: mount

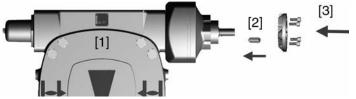
An input mounting flange is required for mounting a multi-turn actuator. Depending on the version, the flange for mounting the multi-turn actuator is already fitted in the factory.

Suitable input mounting flanges

Gearboxes	Reduction ratio	Input shaft	Input mounting flange for mounting multi-turn actuators			
		[mm]	EN ISO 5210	DIN 3210		
GS 50.3	51:1	16	F07, F10	G0		
GS 63.3	51:1	20	F07 F40	G0		
65 63.3	82:1	20	F07, F10	GU		
GS 80.3	53:1	20	F07, F10	G0		
65 00.5	82:1	20	107,110	60		
	52:1	30/(20)	F14 (F10)	G1/2 (G0)		
	107:1 ¹⁾	30	F14 (F10)	G1/2 (G0)		
GS 100.3	126:1 ¹⁾	30	F10	G0		
	260:1 ¹⁾	30	F10	G0		
	208:1 ¹⁾	30	F10	G0		
	52:1	30	F14	G1/2		
GS 125.3	126:1 ¹⁾	30/(20)	F14 (F10)	(G0)		
GS 125.3	160:1 ¹⁾	30/(20)	F14 (F10)	(G0)		
	208:1 ¹⁾	20	F10, F14	G0		
	54:1	30	F16 (F14)	G3 (G1/2)		
GS 160.3	218:1 ¹⁾	30/(20)	F14 (F10)	G1/2 (G0)		
65 100.5	442:1 ¹⁾	20	F10	G0		
	880:1 ¹⁾	20	F10	G0		
	53:1	40	F25 (F16)	(G3)		
	1)	30	F14	G1/2		
GS 200.3	434:1 ¹⁾	30/(20)	F14 (F10)	G1/2 (G0)		
	864:1 ¹⁾	20	F14	G0		
	1,752:1 ¹⁾	20	F10	G0		
	52:1	50	F30 (F25)	-		
	210:1 ¹⁾	40/(30)	F16 (F14)	G3 (G1/2)		
GS 250.3	411:1 ¹⁾	30	F14	G1/2		
	848:1 ¹⁾	30/(20)	F14 (F10)	G1/2 (G0)		
	1 718:1 ¹⁾	20	F10	G0		

1) Equipped with primary reduction gearing or planetary gearing to reduce input torques.

Assembly steps 1. Clean mounting faces, thoroughly degrease uncoated mounting surfaces. Figure 6: Mounting example, input mounting flange fitted to gearbox with primary reduction gearing



- [1] Gearbox with primary reduction gearing
- [2] Parallel pin
- [3] Input mounting flange
- 2. Mount parallel pin [2].
- 3. Place input mounting flange [3] and fasten with screws.

4. Fasten screws crosswise to a torque according to table.

Table 3:

Tightening torques for screws (for mounting multi-turn actuator and input mounting flange)					
Threads	Tightening torque Nm]				
	Strength class A2-80				
M8	24				
M10	48				
M12	82				
M16	200				
M20	392				

5. Mount AUMA actuator in compliance with the operation instructions pertaining to the multi-turn actuator.

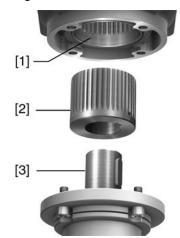
4.4. Gearbox to valve: mount

The gearbox is mounted to the valve using a coupling (standard) or via lever. Separate instructions are available for actuator mounting to the valve when equipped with base and lever.

4.4.1. Output drive for coupling

Application

- For valves with connections according to EN ISO 5211
 For rotating, non-rising valve stem
- **Design** Figure 7: Valve attachment via coupling



- [1] Gearbox output drive shaft with internal splines
- [2] Splined plug-in coupling
- [3] Valve shaft (example with keyway and key)

4.4.1.1. Gearbox with coupling: mount to valve

Unbored couplings or couplings with pilot bore must be machined to match the valve shaft prior to mounting the gearbox to the valve (e.g. with bore and keyway, two-flat or square bore).

Information Assemble valve and gearbox in the same end position. As a standard, the gearbox is supplied in end position CLOSED.

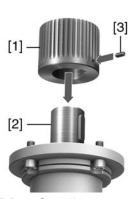
- Recommended mounting position for butterfly valves: End position CLOSED.
- Recommended mounting position for **ball valves**: End position OPEN.

Assembly steps 1. If required, move gearbox in same end position as valve using the handwheel.

- 2. Clean mounting faces, thoroughly degrease uncoated mounting surfaces.
 - 3. Apply a small quantity of grease to the valve shaft [2].

4. Fit coupling [1] onto valve shaft [2] and secure against axial slipping by using a grub screw [3] or a washer and a screw [4]. Thereby, ensure that dimensions X, Y or L are observed (refer to figure and table <Mounting positions for coupling>).

Figure 8: Examples: Fit coupling



- [1] Coupling
- [2] Valve shaft
- [3] Grub screw
- [4] Screw with washer

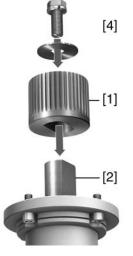
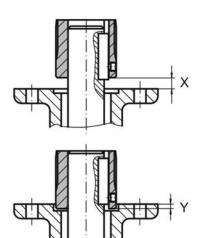
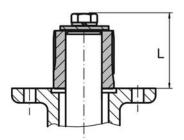


Figure 9: Mounting positions for coupling





Tab	1 -	Λ.
Iar	Me.	<u>4</u> .

Dimensions [mm]	GS 50.3		50.3 GS 63.3 GS 80.3		3	GS 100.3		GS 125.3			
EN ISO 5211	F05	F10	F10	F12	F12	F14	F14	F16	F16	F25	F30 ¹⁾
X max.	6	14	7	10	13	23	22	22	17	17	35
Y max.	5	5	18	13	18	5	13	8	35	27	0
L max.	61	61	61	73	76	78	88	123	123	126	126

1) Extension flange, extended coupling required

Table 5:										
Dimensions [mm]	GS 160.3			GS 200.3	3		GS 250.3			
EN ISO 5211	F25	F30 ¹⁾	F35	F30	F35	F40 ¹⁾	F35	F40	F48 ¹⁾	
X max.	15	30	30	19	44	44	8	13	20	
Y max.	11	0	0	19	0	0	8	0	5	
L max.	130	140	130	160	190	160	220	230	220	

1) Extension flange, extended coupling required

- 5. Apply non-acidic grease at splines of coupling (e.g. Gleitmo by Fuchs).
- 6. Experience showed that it is very difficult to fasten screws or nuts of size M30 or larger at defined torques. There is a risk that the worm gearbox might shift radially with regard to the valve mounting flange. To improve adhesion between valve and gearbox, we recommend to apply Loctite 243 (or similar adhesive products) to the mounting faces of screws and nuts from size M30.
- 7. Fit gearbox. If required, slightly turn gearbox until splines of coupling engage. Figure 10:



- **Information** Ensure that the spigot (if provided) fits uniformly in the recess and that the flanges are in complete contact.
 - 8. If flange bores do not match thread:
 - 8.1 Slightly rotate handwheel until bores line up.
 - 8.2 If required, shift gearbox position by one tooth on the coupling.
 - Fasten gearbox with screws.
 Information: We recommend applying liquid thread sealing material to the screws to avoid contact corrosion.

10. Fasten screws crosswise to a torque according to table.

Table 6:								
Tightening torques for screws								
Threads	Tightening torque Nm]							
	Strength class							
	A2-70/A4-70	A2-80/A4-80						
M6	8	10						
M8	18	24						
M10	36	48						
M12	61	82						
M16	150	200						
M20	294	392						
M30	564	1,422						
M36	2,098	2,481						

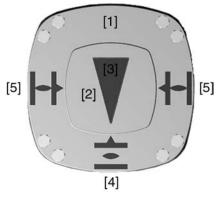
5. Indications

5.1. Mechanical position indicator/running indication

Mechanical position indicator:

- continuously indicates the valve position (pointer cover [2] follows the valve movement)
- indicates whether the actuator is moving (running indication)
- indicates that end positions have been reached (mark on pointer cover [3] points to symbols OPEN [4] or CLOSED [5])

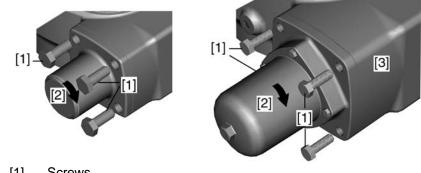
Figure 11: Mechanical position indicator



- [1] Housing cover
- [2] Pointer cover
- [3] Indicator mark
- [4] Symbol for position OPEN
- [5] Symbol for position CLOSED

6.	Commissioni	ng							
6.1.	End stops in ge	arbox							
		The internal end stops limit the swing angle and protect the valve against overload.							
		End stop setting is generally performed by the valve manufacturer prior to installing the valve into the pipework.							
		Exposed, rotating parts (discs/balls) at the valve!							
		Pinching and damage at the valve.							
		ightarrow End stops should be set by suitably qualified personnel only.							
		ightarrow Set end stops as to ensure that they are NOT reached during normal operation.							
	Information	The setting sequence depends on the valve:							
		 Recommendation for butterfly valves: Set end stop CLOSED first. 							
		Recommendation for ball valves : Set end stop OPEN first.							
	Information	 In general, gearboxes with a swing angle > 190° are multi-turn (without end stops). Consequently, end position setting is not possible. Therefore, no protect- ive function is available for the valve. 							
		• In general, only one end stop (either OPEN or CLOSED) must be set, due to the fact that the swing angle was already set in the factory.							
6.1.1	. End stop CLOS	ED: set							
		Figure 12: End stop (left: up to size 125.3, right: from size 160.3)							

Figure 12: End stop (left: up to size 125.3, right: from size 160.3)



- [1] Screws
- [2] End stop
- [3] Housing
- 1. Remove the four screws [1] at end stop [2].

NOTICE

No overload protection at valve for unfastened end stop!

- → In motor operation: Stop travel before reaching the valve end position (consider overrun).
- $\rightarrow~$ The last part of the travel must be completed in manual operation mode.
- 2. Turn valve via handwheel to position CLOSED. Check whether end stop [2] rotates simultaneously.
 - \rightarrow Otherwise: Turn end stop [2] **clockwise** to the stop.

- 3. With mounted multi-turn actuator (not required for manual operation): Turn end stop [2] counterclockwise by 1/4 turn.
- This ensures that the gearbox end stop cannot be approached during motor operation if a multi-turn actuator is mounted and that the valve can close tightly for torque seating.
- 4. In case the four holes of the end stop [2] do not match the four threaded bores within the housing [3]: Remove end stop [2] until it disengages from the toothing and replace in correct position.
- 5. Fasten screws [1] crosswise with a torque according to table < Tightening torques for screws at end stop> .

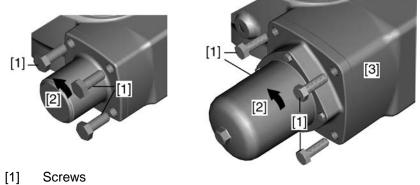
Table 7:									
Tightening torques for screws at end stop									
Gearbox	Screws [1]	Tightening torque T _A [Nm]							
GS 50.3	M6	10							
GS 50.3 – GS 80.3	M8	24							
GS 100.3 – GS 125.3	M12	82							
GS 160.3	M10	48							
GS 200.3	M12	82							
GS 250.3	M16	200							

Further settings hereafter:

- If the gearbox is equipped with a pointer cover: Check whether the mark aligns with the symbol CLOSED. Refer to <Mechanical position indicator: set>.
- If the gearbox is mounted to a multi-turn actuator, set the seating in end position CLOSED straight after completion of the current setting: <Seating in end positions via multi-turn actuator>.

6.1.2. End stop OPEN: set

Figure 13: End stop (left: up to size 125.3, right: from size 160.3)



- [2] End stop
- [3] Housing
- 1. Remove the four screws [1] at end stop [2].

NOTICE

No overload protection at valve for unfastened end stop!

- In motor operation: Stop travel before reaching the valve end position (consider \rightarrow overrun).
- The last part of the travel must be in manual operation mode.
- 2. Turn valve via handwheel in position OPEN. Check whether end stop [2] rotates simultaneously.
 - Otherwise: Turn end stop [2] counterclockwise to the stop.

- 3. With mounted multi-turn actuator (not required for manual operation): Turn end stop [2] clockwise by 1/4 turn.
- This ensures that the gearbox end stop cannot be approached during motor operation if a multi-turn actuator is mounted and that the valve can close tightly for torque seating.
- 4. In case the four holes of the end stop [2] do not match the four threaded bores within the housing [3]: Remove end stop [2] until it disengages from the toothing and replace in correct position.
- 5. Fasten screws [1] crosswise with a torque according to table <Tightening torques for screws at end stop>.

Further settings hereafter:

- If the gearbox is equipped with a pointer cover: Check whether the mark aligns with the symbol OPEN. Refer to <Mechanical position indicator: set>.
- If the gearbox is mounted to a multi-turn actuator, set the seating in end position OPEN straight after completion of the current setting: <Seating in end positions via multi-turn actuator>.

6.2. Seating in end positions via multi-turn actuator

This chapter supplies basic information and notes which should be considered in addition to the operation instructions of the multi-turn actuator.

- The valve manufacturer has to determine whether the valve is limit or torque seated.
- End position seating must be set in compliance with the operating instructions pertaining to the multi-turn actuator.
- When setting the torque switching within the multi-turn actuator, make sure that the tripping torque for both directions does not exceed the max. gearbox input torque (refer to technical data or name plate).
- Set the torque switching within the multi-turn actuator to the following value to prevent damage to the valve:
 - Tripping torque = valve torque/factor (refer to name plate)
- If the swing angle set in the factory for opening and closing the valve is not sufficient: refer to <Swing angle>.

6.2.1. Seating in end position CLOSED: set

- Move valve to end position CLOSED.
 Information: The last part of the travel must be in manual operation mode!
- 2. For limit seating in end position CLOSED:
 - 2.1 Turn back the valve from the valve end position by an amount equal to the overrun.
 - 2.2 Set limit switching for the end position CLOSED according to the operation instructions for the multi-turn actuator.
- 3. For torque seating in end position CLOSED:
 - 3.1 Gearbox without primary reduction gearing: Turn handwheel in the opposite direction of the valve end position by approx. 4 6 turns.
 - 3.2 Gearbox with primary reduction gearing: Turn handwheel in the opposite direction of the valve end position by approx. 10 15 turns.
 - 3.3 Check torque switching for end position CLOSED according to operation instructions for multi-turn actuator and, if necessary, set to required value.
 - 3.4 Set limit switching for signalling end position CLOSED according to operation instructions for multi-turn actuator.

6.2.2.	Seating in end p	ositio	n OPEN: set
			Move valve to end position OPEN. Information: The last part of the travel must be in manual operation mode!
		2.	For limit seating in end position OPEN:
			2.1 Turn back the valve from the valve end position by an amount equal to the overrun.
			2.2 Set limit switching for end position OPEN according to the operation in- structions for the multi-turn actuator.
		3.	For torque seating in end position OPEN:
			3.1 Gearbox without primary reduction gearing: Turn handwheel in the opposite direction of the valve end position by approx. 4 – 6 turns.
			3.2 Gearbox with primary reduction gearing: Turn handwheel in the opposite direction of the valve end position by approx. 10 − 15 turns.
			3.3 Check torque switching for end position OPEN according to operation in- structions for multi-turn actuator and, if necessary, set to required value.
			3.4 Set limit switching for signalling end position OPEN according to operation instructions for multi-turn actuator.
6.3.	Swing angle		
		The suffic	swing angle must only be changed if the swivel range for end stop setting is not cient.
		Figur	re 14: Name plate indicating the swing angle
		auma	Nr : 0512CG12345 i= 53:1 80°- 100° Factor: 19,3 Vers: RR T max: 1 400 Nm Lubr: F15 IP 68-3
	Versions	Sizes	s GS 50.3 – GS 125.3 = adjustable swing angle - option
		Sizes	s GS 160.3 – GS 250.3 = adjustable swing angle - standard
	Accuracy	Sizes	s GS 50.3 – GS 125.3 = 0.6°

Sizes GS 160.3 - GS 250.3 = 0.11° up to 0.14°

6.3.1. Swing angle: modify at gearboxes up to size 125.3

The adjustment is made in end position OPEN.

Special tools: Pin drive for spring-type straight pin

- for GS 50.3 (AUMA art. no. V001.367-Pos.003)
- for GS 63.3 GS 80.3 (AUMA art. no. V001.367-Pos.002)
- for GS 100.3 GS 125.3 (AUMA art. no. V001.367-Pos.001)

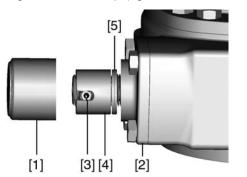
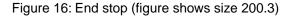


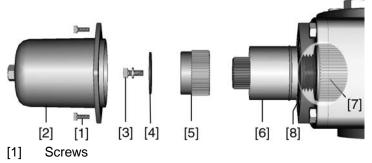
Figure 15: End stop (figure shows size 80.3)

- [1] Protective cap
- [2] End stop
- [3] Spring-type straight pin
- [4] End stop nut
- [5] Pairs of safety wedge discs (for OPEN and CLOSE)
- 1. Unscrew protective cap [1] at end stop [2].
- 2. Remove spring-type straight pin [3] with suitable pin drive (special tool).
- 3. Swing angle increase:
 - 3.1 Turn end stop nut [4] **counterclockwise**. **Information:** When turning counterclockwise the end stop nut [4] make sure that the spring-type straight pin [3] can still be tapped within the oblong hole.
 - 3.2 Move valve manually to the desired end position OPEN.
 - 3.3 Turn end stop nut [4] **clockwise** until it is tight to the travelling nut.
- 4. Swing angle reduction:
 - 4.1 Move valve manually to the desired end position OPEN.
 - 4.2 Turn end stop nut [4] clockwise until it is tight to the travelling nut. Information: Spring-type straight pin [3] must remain completely covered by end nut [4].
- 5. Drive in the spring-type straight pin [3] using the appropriate tool.
 - → If the slot provided in the end stop nut [4] does not align with the bore of the worm shaft: Turn end stop nut [4] slighty counterclockwise until the hole is aligned; then drive in spring-type straight pin [3].
- 6. Check whether O-ring at protective cap is in good condition, replace if damaged.
- 7. Fasten protective cap [1].
- **Information** If the gearbox is mounted to a multi-turn actuator, the limit switching for the end position OPEN must be set first in compliance with the operation instructions of the multi-turn actuator. Allow for overrun!

6.3.2. Swing angle: modify at gearboxes from size 160.3

Adjustments are generally made in end position OPEN.

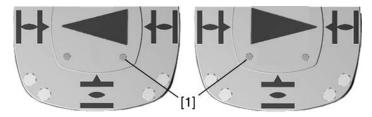




- [2] Protective cap
- [3] Screw with washer
- [4] Clamping washer
- [5] Setting ring
- [6] End stop nut
- [7] Travelling nut
- [8] Pairs of safety wedge discs (for OPEN and CLOSE)
- 1. Remove all four screws [1] and pull off protective cap [2].
- 2. Remove the screw with the washer [3] and clamping washer [4].
- 3. Pull off setting ring [5].
- 4. Swing angle increase:
 - 4.1 Turn end stop nut [6] counterclockwise.
 - 4.2 Move valve manually to the desired end position OPEN.
 - 4.3 Turn end stop nut [6] **clockwise** until it is tight to the travelling nut [7].
- 5. Swing angle reduction:
 - 5.1 Move valve manually to the desired end position OPEN.
 - 5.2 Turn end stop nut [6] clockwise until it is tight to the travelling nut [7].
- 6. Fit setting ring [5], secure with clamping washer [4], washer and screw [3].
- 7. Check whether O-ring at protective cap is in good condition, replace if damaged.
- 8. Place protective cap [2] and fasten screws [1] crosswise with a torque according to table <Tightening torques for screws at end stop>.
- **Information** If the gearbox is mounted to a multi-turn actuator, the limit switching for the end position OPEN must be set first in compliance with the operation instructions of the multi-turn actuator.

6.4. Mechanical position indicator: set

- 1. Move valve to end position CLOSED and check setting.
- The setting is correct if the mark aligns with the symbol CLOSED.



End position OPEN

- 2. If the mark position is not correct:
 - 2.1 Slightly loosen screws [1] at pointer cover [two screws up to size 125.3, four screws as from size 160.3).
 - 2.2 Turn pointer cover to symbol for position CLOSED [5].
 - 2.3 Fasten screws again.
- 3. Move valve to end position OPEN and check setting.
- → The setting is correct if the mark aligns with the symbol OPEN.

7.	Servicing and	I maintenance
	CAUTION AUMA Service & Support	 Damage caused by inappropriate maintenance! → Servicing and maintenance must be carried out exclusively by suitably qualified personnel having been authorised by the end user or the contractor of the plant. Therefore, we recommend contacting our service. → Only perform servicing and maintenance tasks when the device is switched off. AUMA offer extensive service such as servicing and maintenance as well as customer product training. For the relevant contact addresses, please refer to <addresses> in this document or to the Internet (www.auma.com).</addresses>
7.1.	Preventive meas	sures for servicing and safe operation
		 Before commissioning, perform visual inspection for grease leakage and paint damage (corrosion). Thoroughly touch up any possible damage to paint. Original paint in small quantities can be supplied by AUMA.
7.2.	Maintenance inter	ervals
		Recommendation for plants subject to strong vibration
		 For plants subject to strong vibration, 6 months after commissioning and then once a year: Check fastening screws between actuator and gearbox/valve for tightness. If required, fasten screws while applying the tightening torques as indicated in chapter <assembly>. For screws sealed and secured with e.g. thread sealing material, this action is not required.</assembly> Recommendation for grease change and seal replacement:
		 If rarely operated (typically in buried service), the gearboxes are maintenance-
		free. Grease change or re-lubrication is not necessary.
		 If operated frequently (typically in modulating duty), we recommend changing both grease and seals after 4 – 6 years.
	NOTIOES	Gearing damage due to using inappropriate grease!
	NOTICE	\rightarrow Only use original lubricants supplied by AUMA.
		\rightarrow Do not mix lubricants.
		Instructions for use in potentially explosive atmospheres of categories M2,
		2G, 3G, 2D and 3D
		• Imperatively heed the technical data, as well as the ambient temperatures, type of duty and running times indicated on the name plate are observed.
		• In potentially explosive atmospheres, in particular where combustible dust is present, perform visual inspection for deposit of dirt or dust on a regular basis. Clean devices if required.
		• The pointer cover is only approved for use in potentially explosive atmospheres according to ATEX II2G c IIB T4 or T3.
		 When using mechanical microswitches (option), additionally observe the mounting and wiring instructions of the manufacturer.
7.3.	Disposal and ree	cycling
		Our devices have a long lifetime. However, they have to be replaced at one point in time. The devices have a modular design and may, therefore, easily be separated and sorted according to materials used, i.e.:

- electronic scrap
- various metals
- plastics

• greases and oils

The following generally applies:

- Greases and oils are hazardous to water and must not be released into the environment.
- Arrange for controlled waste disposal of the disassembled material or for separate recycling according to materials.
- Observe the national regulations for waste disposal.

8.	Technical dat	a
	Information	The following tables include standard and optional features. For detailed information
		on the customer-specific version, refer to the order-related data sheet. The technical
		data sheet can be downloaded from the Internet in both German and English at ht-
		tp://www.auma.com (please state the order number).

8.1. Technical data Part-turn gearboxes

General information

For motor or manual operation of valves (e.g. butterfly valves, ball and plug valves). For special applications, e.g. dampers, gas diverters, flue gas dampers, toggle arm driven diverters and guillotine isolators, special sizing is required. Special technical data apply for special applications. Available special applications on request.

Features and functions												
Worm wheel material	Open-close duty:	Spher	oidal cast i	ron								
	Modulating Bronze duty:											
Version	Standard: Clockwise rotation RR, counterclockwise rotation LL											
	Option:	RL or	LR									
Housing material	Standard:	Cast i	ron (GJL-2	50)								
	Option:	Spher	oidal cast i	ron (GJS-	400-	15)						
Self-locking	The gearboxes are self-locking when at standstill under normal service conditions; strong vibration may cancel the self-locking effect. While in motion, safe breaking is not guaranteed. If this is required, a separate brake must be used.											
End stops	Positive for b	oth end	d positions	by travelli	ng nu	ut, sensi	tive adj	ustment				
Strength of end stop	Guaranteed strength of end stop (in Nm) for input side operation											
	Туре		GS 50.3	GS 63	.3	GS 80.3	3		GS 1	00.3		
	Reduction ra	atio	51:1	51:1		53:1	5	52:1	126:1	160:1	208:1	
	[Nm]		250	450		450	1	350	625	500	250	
	Туре			GS 125.					GS	5 160.3		
	Reduction ra	atio	52:1	126:1	160		08:1	54:1	218:1	442:1	880:1	
	[Nm]		1350	625	500	2	50	3200	900	450	250	
	Туре		50.4	07.4	07.4		GS 200.3		004		1750 4	
	Reduction ra	atio	53:1	67:1 250		214:1		434:1	864		1752:1	
	[Nm]		8000 2			2000) 1000		500		250	
	Type GS 250.3											
	Type Reduction ra	atio	52:1	21(210:1		411:1		848:1	17	18:1	
	[Nm]	110	8000							25		
			8000 2000			1000		200 200		0		
Swing angle GS 50.3 – GS 125.3	Standard: Fixed swing angle between 10° and max. 100°; set in the factory to 92° unless ordered otherwise.											
	Options: Adjustable in steps of: 10° – 35°, 35° – 60°, 60° – 80°, 80° – 100°, 100° – 125°, 125° – 150°, 150° – 170°, 1								– 170°,170°			
		 – 190° Swing angle > 190°, refer to Technical data GS 50.3 – GS 250.3 for modulating duty a shorter operating times 									ting duty and	
Swing angle GS 160.3 – GS 250.3	Standard:	Adjus	table 80° -	100°; set	in th	e factory	/ to 92°	unless o	ordered oth	erwise.		
	Options: Adjustable in steps of: $0^{\circ} - 20^{\circ}, 20^{\circ} - 40^{\circ}, 40^{\circ} - 60^{\circ}, 60^{\circ} - 80^{\circ}, 90^{\circ} - 110^{\circ}, 110^{\circ} - 130^{\circ}, 130^{\circ} - 150^{\circ}, 150^{\circ} - 170^{\circ}, 170^{\circ} - 190^{\circ}$ Swing angle > 190°, refer to Technical data GS 50.3 – GS 250.3 for modulating duty and shorter operating times											
Swing angle at special reduction	Standard:	Adjus	table 80° -	100°; set	in th	e factory	/ to 92°	' unless o	ordered oth	erwise.		
ratio GS 200.3 - 67:1	Options:	0° – 2	, 0	0°, 40° – 6				end sto	ps, GSD ve	rsion, spe	cific sizing	

Features and functions												
Mechanical position indicator	Standard: Point	er cover	for	continu	ious po	osition i	ndication					
	Options: • S	ealed p	ointe	er covei	r for ho	orizonta	l outdoor	installati	ion (not	available	e for G	\$ 50.3)
		rotectio ion indic			buried	service	s instead	of pointe	er cover	(without	mecha	inical pos-
	• Sealed pointer cover with air vent valve, not available for GS 50.3											
	Observe notes on Information sheet Enclosure protection IP68 for part-turn gearboxes											arboxes
Input shaft	Cylindrical with par	allel key	acc	ording	to DIN	 6885- 1						
Operation												
Motor operation	 Via electric mu 	ti-turn a	ictua	ator								
	Input mounting flanges for mounting multi-turn actuators											
Type of duty	duty: Class		ording	g to EN	1571		EN-CLOS		r positio	ning dut	у	
		nittent c C acco				4-2: Mo	dulating o	luty				
Maximum permissible input speeds and operating times	Modulating duty: 2' Open-close duty:	Modulating duty: 215 rpm										
	Туре			G	S 125.	3				GS 160.	3	
	Reduction ratio	52:	1	126:1		160:1 208:1		54:1	218	3:1 442:1		880:1
	Max. permissible input speed [rpm]	108	3			216		108		216		
	Fastest operating time for 90° [s]	1350		625	50	0	250	3200	900	45	0	250
	Туре	GS 50.3			3.3	GS 80.3				GS 100.3		
	Reduction ratio	51:1	5	51:1	82:1	53:1	82:1	52:1	107:1	126:1	160:1	208:1
	Max. permissible input speed [rpm]	108		108	3	108		108			216	
	Fastest operating time for 90° [s]	7		7	11	7	11	7	15	9	11	19
	_				-							
	Туре	50.4	-		S 200		1750 1	50.4		GS 250.		4740.4
	Reduction ratio Max. permissible in put speed [rpm]	53:1 ¹⁻ 108		14:1		864:1 216	1752:1	108	210:1	411:1	848:1 16	1718:1
	Fastest operating time for 90° [s]	7	1	5	30	60	122	7	15	29	59	119
	Due to gear tooth g wheel made of bro						teristics c	of bronze	e, worm	gearbox	es with	a worm
	Calculation of oper					•	nent					
	Oper. time for 90° [s]	=		uction ra ut speed			15					
	Calculation of the c						nent [°]:					
	Oper. time for $\theta^{p}[s]$	Swin	gan	gle 0 [*]	• Redu	iction ra in rpm]	tio [j]					

Operation											
Manual operation	 Handwheel made of aluminium with electrophoretic coating Handwheel with ball handle 										
	 Option: Handwheel made of GJL-200 with electrophoretic coating and painting Handwheel lockable WSH for signalling position and end positions Available handwheel diameters according to EN 12570, selection according to output torque:										
							n accc	nuing to			
	Туре	GS 50.3	GS 63.3	GS 80.3		GS 100.3			GS		
	Reduction ratio	51:1	51:1	53:1	52:1 [·]	126:1 160:	1 208:	1 52:1	126:	1 160:1	208:1
	Handwheel Ø [mm]	160 200 250	250 315	315 400	400 500	315 400				400 500	315 400
	-										
	Туре			160.3				GS 200.3			
	Reduction ratio	54:1	218:1	442:1	880:1	53:1 6	7:1		434:1	864:1	1752:1
	Handwheel Ø [mm]	630 800	400	315	250	-	800	500 630	400	315	250
	Туре		GS 250.3								
	Reduction ratio	52:1		210	:1	411:1	411:1		848:1		
	Handwheel Ø [mm]		-		800		500 630		400		15

Deflection of the input shaft

90° deflection of the input shaft Combination with GK bevel gearbox directly mounted on GS or on planetary stage possible, refer to Mounting positions Part-turn gearboxes with multi-turn actuators

Version with base and lever								
Not suitable for load class 3.								
Base	Made of sph	Made of spheroidal cast iron; for mounting to base, 4 holes for fastening screws are available.						
Lever		Made of spheroidal cast iron; with 2 or 3 bores for fixing lever arrangement. Considering the environ- mental conditions, the lever may be mounted to the output shaft in any desired position.						
Ball joints		ts matching the lever, as an option including lock nuts and 2 welding nuts; suitable for pipe dimension sheet.						
Mechanical position indicator	Standard:	No position indicator (protection cover)						
	Option:	Pointer cover instead of protection cover for continuous position indication						

Valve attachment	Dimensions according to EN ISO 5211: The maximum torques of mounting flanges according to EN ISO 5211 are to be met.											
Spigot	Flanges with spigot, recess or plane flanges are available. Up to GS 125.3, spigots are implemented by means of spigot rings. From GS 160.3 to GS 250.3, recesses and spigots are directly integrated into the housing.											
Bore for locating pins (option)	Two bores for locating pins shifted by 180°. The locating pins are not included in the scope of delivery.											
	Туре		GS 80.3		GS 100.3		GS 125.3		3	GS 160.3		3
	Flange accor EN ISO 521		F12	F14	F14	F16	F16	F25	F30	F25	F30	F35
	Housing mat	terial	GJS	GJS	GJS	GJS	GJL	GJL	GJL	GJL	GJL	GJL
	Туре		GS 200.3				GS 250.3					
	Flange according to EN ISO 5211		F	30	F35		F40	F3	5	F40		F48
	Housing mat	terial GJL		JL	GJL		GJL		IL	GJL GJL		GJL
	Refer to dimension drawing U4.4135. Further pitch circle diameters and bore depths for locating pins on request											
Splined coupling for connection to	Standard: • Without bore or pilot bore from GS 160.3											
the valve shaft		• Wo	orm gea	rbox car	n be mou	inted on	coupling	9				
	Options: Finish machining with bore and keyway, square bore or two-flat with grub screw for secure fixing to valve shaft.											
		0										
Service conditions												
Mounting position	Any position											
•••	Any position	–40 °C	to +80	°C								
•.	Any position II2D c T130°C	–60 °C 0 °C to Note: V	to +60 +120 °(Vhen us	°C C sing med			itches, tl	ne tempe	erature r	anges in	dicated	here are
Ambient temperature Enclosure protection according to	ll2D c	-60 °C 0 °C to Note: V reduce	to +60 +120 °(Vhen us d to -30	°C C sing mec) °C up t	hanical ı o max. + ater-tight	-90 °C.				anges in	dicated	here are
Ambient temperature Enclosure protection according to	II2D c T130°C	-60 °C 0 °C to Note: V reduce IP68, d	to +60 +120 °(Vhen us d to –30 lust-tigh	°C C sing mec) °C up t t and wa	o max. +	-90 °C. up to m	iax. 8 m	head of	water	-	dicated	here are
Ambient temperature Enclosure protection according to EN 60529	II2D c T130°C Standard:	-60 °C 0 °C to Note: V reduce IP68, d IP68-20 GS 50.	to +60 +120 °(Vhen us d to –30 lust-tigh 0, dust-1 3 – GS	°C C sing mec) °C up t t and wa	o max. + ater-tight I water-ti S	-90 °C. up to m	iax. 8 m	head of	water	-	dicated	here are
Ambient temperature Enclosure protection according to EN 60529	II2D c T130°C Standard: Options:	-60 °C 0 °C to Note: V reduce IP68, d IP68-20 GS 50. GS 100 GS 50.	to +60 +120 °(Vhen us d to -30 lust-tigh 0, dust-t 3 - GS 3 - GS 3 - GS	°C C sing mec) °C up t t and wa tight and 80.3: KS	o max. + ater-tight I water-ti S KN KN	-90 °C. up to m	iax. 8 m	head of	water	-	dicated	here are
Ambient temperature Enclosure protection according to EN 60529	II2D c T130°C Standard: Options: Standard:	-60 °C 0 °C to Note: V reduce IP68, d IP68-20 GS 50. GS 100 GS 50. GS 100	to +60 +120 °(Vhen us d to -30 lust-tigh 0, dust-1 3 - GS 0.3 - GS 3 - GS 0.3 - GS 0.3 - GS	°C C sing mec) °C up t t and wa tight and 80.3: KS S 250.3: 80.3: KX S 250.3:	o max. + ater-tight I water-ti S KN KN	·90 °C. up to m ght up t	ax. 8 m o max. 2	head of v 0 m head	water d of wate	er		
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Ambient temperature Enclosure protection according to EN 60529 Corrosion protection	II2D c T130°C Standard: Options: Standard: Options: KN KS	-60 °C 0 °C to Note: V reduce IP68, d IP68-20 GS 50. GS 100 GS 50. GS 100 Suitabl concen Suitabl pollutio Suitabl pollutio	to +60 +120 °° Vhen us d to -30 lust-tigh 0, dust-1 3 - GS 3 - GS 3 - GS 3 - GS 3 - GS 3 - GS e for ins tration e for us n. e for us n.	°C C C ing mec) °C up t t and wa tight and 80.3: KS S 250.3: 80.3: KS S 250.3: tallation e in area	o max. + ater-tight I water-ti S KN KS/KX in indus as with h	·90 °C. up to m ght up t trial uni igh salir	ax. 8 m o max. 2 ts, in wat	head of to 0 m head ter or port	water d of wate wer plan anent cc	er Its with a	I low pol	lutant I high
Mounting position Ambient temperature Enclosure protection according to EN 60529 Corrosion protection	II2D c T130°C Standard: Options: Standard: Options: KN KS KX	-60 °C 0 °C to Note: V reduce IP68, d IP68-20 GS 50. GS 100 GS 50. GS 100 Suitabl concen Suitabl pollutio Suitabl pollutio S \$0.3: F	to +60 +120 °C Vhen us d to $-3C$ lust-tigh 0, dust-tigh 0, dust-tigh	°C C C ing mec) °C up t t and wa tight and 80.3: KS S 250.3: 80.3: KS S 250.3: stallation e in area coating	o max. + ater-tight I water-ti S KN (KS/KX in indus as with h	90 °C. up to m ght up t trial uni igh salir xtremel	ax. 8 m o max. 2 ts, in wat hity, almo	head of 1 0 m head her or pout her perman	water d of wate wer plan anent cc	er Its with a	I low pol	
Ambient temperature Enclosure protection according to EN 60529 Corrosion protection	II2D c T130°C Standard: Options: Standard: Options: KN KS KX GS 50.3 – GS	-60 °C 0 °C to Note: V reduce IP68, d IP68-20 GS 50. GS 100 GS 50. GS 100 Suitabl concen Suitabl pollutio Suitabl pollutio S 80.3: F	to +60 +120 °C When us d to $-3C$ lust-tigh 0, dust-1 3 - GS 0.3 - GS 0.3 - GS 0.3 - GS 0.3 - GS 0.3 - GS e for ins tration e for us n. Powder 3: Two-c	°C C c, ing mec) °C up t t and wa tight and 80.3: KS S 250.3: 80.3: KS S 250.3: stallation e in area coating ompone	o max. + ater-tight I water-ti S KN (KS/KX in indus as with h	90 °C. up to m ght up t trial uni igh salir xtremely	ax. 8 m o max. 2 ts, in wat hity, almo y high sa nbinatior	head of 1 0 m head her or pout her perman	water d of wate wer plan anent cc	er Its with a	I low pol	lutant I high

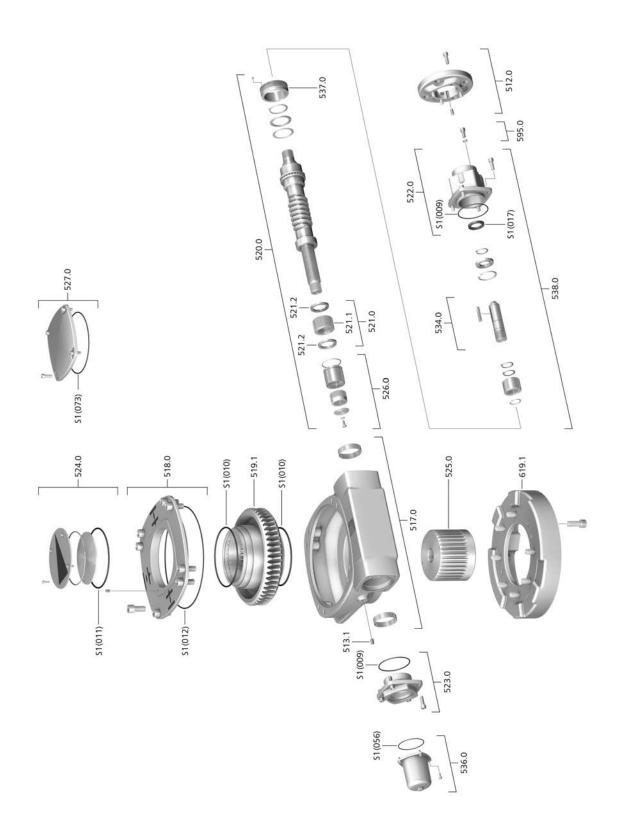
Service conditions								
AUMA load profile	AUMA worm gearboxes meet or exceed the lifetime requirements of EN 15714-2.							
	For open-close duty with worm wheel made of spheroidal cast iron:							
	Peak load (max. output torque)	Ť.						
	Medium load (basic load)	35 % 0 % 35 %	Swivel movement	90° Swing angle				
	Fan waa dudatin a dud	_	made of browns.					
	For modulating duty with worm wheel made of bronze: A start consists of one movement of minimum 1 % in both directions at a load of 35 % of the maximum valve torque (modulating torque).							
Lifetime for motor operation in ac- cordance with AUMA load profile	For open-close duty with worm wheel made of spheroidal cast iron: Duty class 1: Lifetime for 90° swivel movement Meets the lifetime requirement of EN 15714-2							
	Gearbox size	GS 50.3/GS 63.3	GS 80.3/GS100.3	GS 125.3 – GS 200.3	GS 250.3			
	Number of cycles for max. torque	10,000	5,000	2,500	1,200			
	Duty class 2: Lifetime for 90° swivel movement for valves which are infrquently operated.							
	Gearbox size	GS 50.3/GS 63.3	GS 80.3/GS100.3	GS 125.3 – GS 200.3	GS 250.3			
	Number of cycles for max. torque 1,000							
	Lifetime for larger swing angles on request							
	For modulating duty with worm wheel made of bronze: 1.2 million modulating steps							
Lifetime for manual operation	Duty class 3: Meets the lifetime requirement of EN 1074-2							
Further information								
Further information	ATEX Directive: (94/							

9.	Spare parts
9.1.	Part-turn gearboxes GS 50.3 – GS 125.3
51(073)	$\frac{520.3 - 65 80.3}{65 50.3 - 65 80.3}$ $\frac{520.3}{510}$ $\frac{520.3}{510}$ $\frac{510.3}{510}$ 51
-524.0	

Please state device type and our order number (see name plate) when ordering spare parts. Only original AUMA spare parts should be used. Failure to use original spare parts voids the warranty and exempts AUMA from any liability. Delivered spare parts may slightly vary from the representation in these instructions.

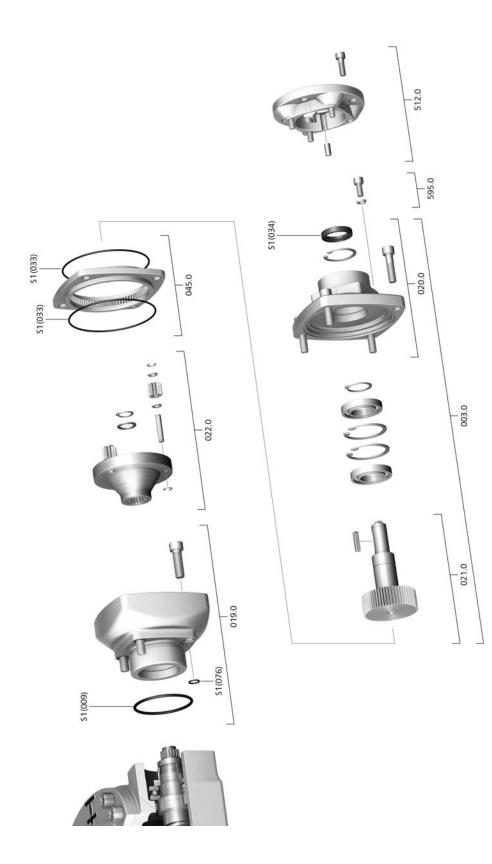
Ref. no.	Designation	Туре
512.0	Input mounting flange	Sub-assembly
517.0	Housing	Sub-assembly
518.0	Housing cover	Sub-assembly
519.1	Worm wheel	
520.0	Worm shaft	Sub-assembly
521.0	Travelling nut with two pairs of safety wedge discs	Sub-assembly
521.1	Travelling nut	
521.12	Pair of safety wedge discs	
522.0	Bearing cover	Sub-assembly
523.0	End stop	Sub-assembly
524.0	Pointer cover	Sub-assembly
525.0	Coupling	Sub-assembly
526.0	End stop nut	Sub-assembly
527.0	Protection cover	Sub-assembly
534.0	Drive shaft	Sub-assembly
538.0	Bearing cover with drive shaft	Sub-assembly
595.0	Screw kit for manual gearbox	Sub-assembly
619.1	Extension flange	Sub-assembly
S1	Seal kit	Set

9.2. Part-turn gearboxes GS 160.3 – GS 250.3



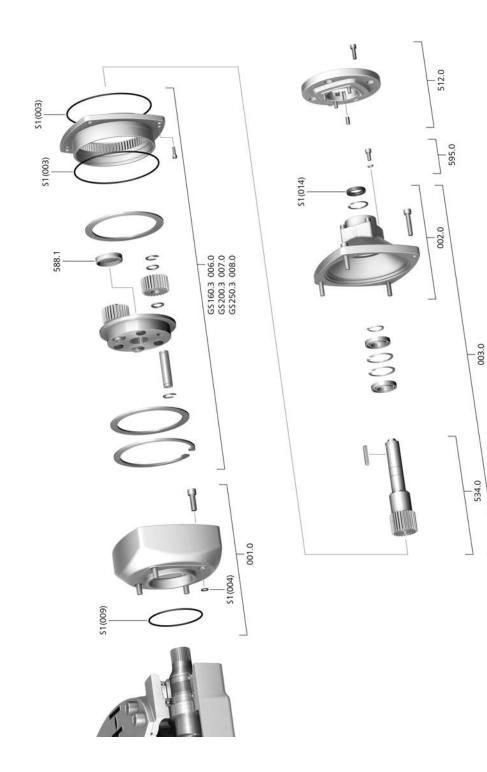
Ref. no.	Designation	Туре
512.0	Input mounting flange	Sub-assembly
513.1	Grub screw	
517.0	Housing	Sub-assembly
518.0	Housing cover	Sub-assembly
519.1	Worm wheel	
520.0	Worm shaft	Sub-assembly
521.0	Travelling nut with two pairs of safety wedge discs	
521.1	Travelling nut	
521.2	Pair of safety wedge discs	Sub-assembly
522.0	Bearing cover	Sub-assembly
523.0	End stop	Sub-assembly
524.0	Pointer cover	Sub-assembly
525.0	Coupling	Sub-assembly
526.0	End stop nut	Sub-assembly
527.0	Protection cover	Sub-assembly
534.0	Drive shaft	Sub-assembly
536.0	Protective cap	Sub-assembly
537.0	Lock nut	Sub-assembly
538.0	Bearing cover with drive shaft	Sub-assembly
595.0	Screw kit for manual gearbox	Sub-assembly
619.1	Extension flange	Sub-assembly
S1	Seal kit	Set

9.3. Primary reduction gearing for GS 100.3 – GS 125.3 (126:1/160:1/208:1)

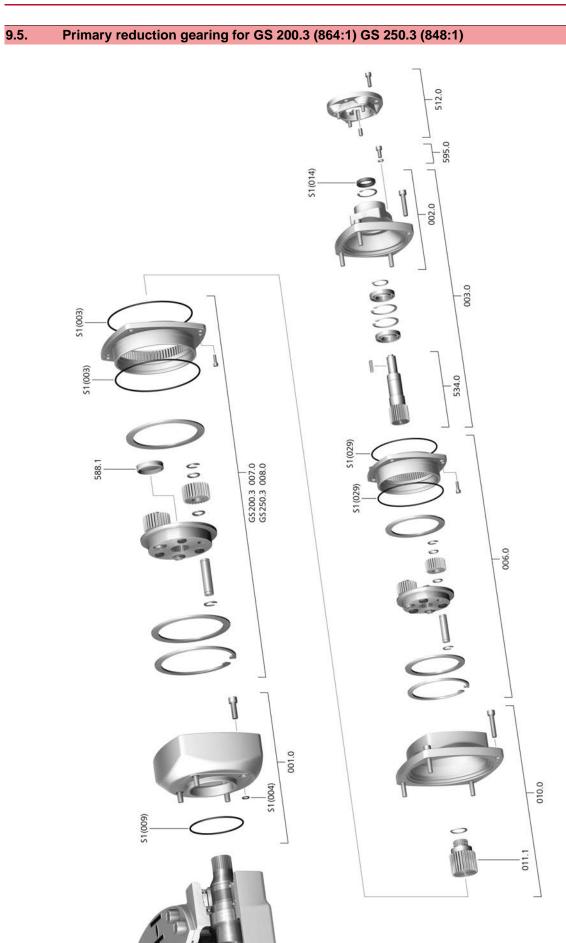


Ref. no.	Designation	Туре
003.0	Housing cover with drive shaft	Sub-assembly
019.0	Housing	Sub-assembly
020.0	Housing cover	Sub-assembly
021.0	Drive shaft	Sub-assembly
022.0	Planet carrier	Sub-assembly
045.0	Internal geared wheel	Sub-assembly
512.0	Input mounting flange	Sub-assembly
595.0	Screw kit for manual gearbox	Sub-assembly
S1	Seal kit	Set

9.4. Primary reduction gearing for GS 160.3 (218:1/442:1) GS 200.3 (214:1/434:1) GS 250.3 (210:1/411:1)



Ref. no.	Designation	Туре
001.0	Housing	Sub-assembly
002.0	Housing cover	Sub-assembly
003.0	Housing cover with drive shaft	Sub-assembly
006.0	Planetary gearing first stage (GS 160.3)	Sub-assembly
007.0	Planetary gearing first stage (GS 200.3)	Sub-assembly
0.800	Planetary gearing first stage (GS 250.3)	Sub-assembly
512.0	Input mounting flange	Sub-assembly
534.0	Drive shaft	Sub-assembly
588.1	Blanking plugs	
595.0	Screw kit for manual gearbox	Sub-assembly
S1	Seal kit	Set



Ref. no.	Designation	Туре
001.0	Housing	Sub-assembly
002.0	Housing cover	Sub-assembly
003.0	Housing cover with drive shaft	Sub-assembly
006.0	Planetary gearing first stage	Sub-assembly
007.0	Planetary gear second stage (GS 200.3)	Sub-assembly
0.800	Planetary gear second stage (GS 250.3)	Sub-assembly
010.0	Intermediate housing	Sub-assembly
011.1	Pinion	
512.0	Input mounting flange	Sub-assembly
534.0	Drive shaft	Sub-assembly
588.1	Blanking plugs	
595.0	Screw kit for manual gearbox	Sub-assembly
S1	Seal kit	Set

10. Certificates

10.1. Declaration of Incorporation and EC Declaration of Conformity

AUMA Riester GmbH & Co. KG
Aumastr. 1
79379 Müllheim, Germany
www.auma.com

Tel +49 7631 809-0 Fax +49 7631 809-1250 Riester@auma.com



Original Declaration of Incorporation of Partly Completed Machinery (EC Directive 2006/42/EC) and EC Declaration of Conformity in compliance with the Directive on Explosion Protection

for AUMA gearboxes of the type ranges

Part-turn gearboxes	GS 50.3 – GS 250.3
3	GS 630.3 with reduction gearing GZ 630.3
	GS 315 – GS 500 with reduction gearing GZ 16.1 – GZ 40.1
Multi-turn gearboxes	GK 10.2 – GK 40.2
	GST 10.1 – GST 40.1
	GP 10.1 – GP 30.1

AUMA Riester GmbH & Co. KG as manufacturer declares herewith, that the above mentioned gearboxes meet the following basic requirements of the EC Machinery Directive 2006/42/EC: Annex I, articles 1.1.2, 1.1.3, 1.1.5, 1.3.1, 1.3.7, 1.7.1, 1.7.3, 1.7.4

The following harmonised standards within the meaning of the Machinery Directive have been applied: EN ISO 12100: 2010 EN ISO 5211: 2001

EN ISO 5210: 1996

With regard to the partly completed machinery, the manufacturer commits to submitting the documents to the competent national authority via electronic transmission upon request. The relevant technical documentation pertaining to the machinery described in Annex VII, part B has been prepared.

AUMA gearboxes are designed to be installed on industrial valves. AUMA gearboxes must not be put service until the final machinery into which they are to be incorporated has been declared in conformity with the provisions of the EC Directive 2006/42/EC.

Authorised person for documentation: Peter Malus, Aumastrasse 1, D-79379 Muellheim

As partly completed machinery in "ATEX" and "Mining" versions, the gearboxes further comply with the requirements of the following directives and the respective approximation of national laws as well as the respective harmonised standards as listed below:

(1) Equipment and protective systems intended for use in potentially explosive atmospheres (94/9/EC)

EN 1127-1: 2011	EN 13463-1: 2009
EN 1127-2: 2014	EN 13463-5: 2011

The above mentioned AUMA gearboxes in "ATEX" and "Mining" versions are marked as follows:

II2G c IIC T4 or T3 II2D IP6X T130°C or T190°C IM2 c I

In order to meet the requirements for use of AUMA gearboxes in potentially explosive atmospheres, the relevant information in the operation instructions must imperatively be observed.

Muellheim 2015-09-01 H/Newerla, General Management

This declaration does not contain any guarantees. The safety instructions in product documentation supplied with the devices must be observed. Non-concerted modification of the devices voids this declaration. Y006.988/003/en

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Europe

AUMA Riester GmbH & Co. KG

Plant Müllheim **DE 79373 Müllheim** Tel +49 7631 809 - 0 riester@auma.com www.auma.com

Plant Ostfildern-Nellingen DE 73747 Ostfildern Tel +49 711 34803 - 0 riester@wof.auma.com

Service-Center Bayern DE 85386 Eching Tel +49 81 65 9017- 0 Riester@scb.auma.com

Service-Center Köln DE 50858 Köln Tel +49 2234 2037 - 900 Service@sck.auma.com

Service-Center Magdeburg DE 39167 Niederndodeleben Tel +49 39204 759 - 0 Service@scm.auma.com

AUMA-Armaturenantriebe Ges.m.b.H. AT 2512 Tribuswinkel Tel +43 2252 82540 office@auma.at www.auma.at

AUMA BENELUX B.V. B. A. BE 8800 Roeselare Tel +32 51 24 24 80 office@auma.be www.auma.nl

ProStream Group Ltd. BG 1632 Sofia Tel +359 2 9179-337 valtchev@prostream.bg www.prostream.bg

OOO "Dunkan-Privod" BY 220004 Minsk Tel +375 29 6945574 belarus@auma.ru www.zatvor.by

AUMA (Schweiz) AG CH 8965 Berikon Tel +41 566 400945 RettichP.ch@auma.com

AUMA Servopohony spol. s.r.o. **CZ 250 01 Brandýs n.L.-St.Boleslav** Tel +420 326 396 993 auma-s@auma.cz www.auma.cz

GRØNBECH & SØNNER A/S DK 2450 København SV Tel +45 33 26 63 00 GS@g-s.dk www.g-s.dk IBEROPLAN S.A. **ES 28027 Madrid** Tel +34 91 3717130 iberoplan@iberoplan.com

AUMA Finland Oy FI 02230 Espoo Tel +358 9 5840 22 auma@auma.fi www.auma.fi

AUMA France S.A.R.L. FR 95157 Taverny Cedex Tel +33 1 39327272 info@auma.fr www.auma.fr

AUMA ACTUATORS Ltd. **GB Clevedon, North Somerset BS21 6TH** Tel +44 1275 871141 mail@auma.co.uk www.auma.co.uk

D. G. Bellos & Co. O.E. **GR 13673 Acharnai, Athens** Tel +30 210 2409485 info@dgbellos.gr

APIS CENTAR d. o. o. HR 10437 Bestovje Tel +385 1 6531 485 auma@apis-centar.com www.apis-centar.com

Fabo Kereskedelmi és Szolgáltató Kft. **HU 8800 Nagykanizsa** Tel +36 93/324-666 auma@fabo.hu www.fabo.hu

Falkinn HF IS 108 Reykjavik Tel +00354 540 7000 os@falkinn.is www.falkinn.is

AUMA ITALIANA S.r.I. a socio unico IT 20023 Cerro Maggiore (MI) Tel +39 0331 51351 info@auma.it www.auma.it

AUMA BENELUX B.V. LU Leiden (NL) Tel +31 71 581 40 40 office@auma.nl

NB Engineering Services **MT ZBR 08 Zabbar** Tel + 356 2169 2647 nikibel@onvol.net

AUMA BENELUX B.V. NL 2314 XT Leiden Tel +31 71 581 40 40 office@auma.nl www.auma.nl

SIGUM A. S. NO 1338 Sandvika Tel +47 67572600 post@sifag.no AUMA Polska Sp. z o.o. PL 41-219 Sosnowiec Tel +48 32 783 52 00 biuro@auma.com.pl www.auma.com.pl

AUMA-LUSA Representative Office, Lda. **PT 2730-033 Barcarena** Tel +351 211 307 100 geral@aumalusa.pt

SAUTECH RO 011783 Bucuresti Tel +40 372 303982 office@sautech.ro

OOO PRIWODY AUMA **RU 141402 Khimki, Moscow region** Tel +7 495 221 64 28 aumarussia@auma.ru www.auma.ru

OOO PRIWODY AUMA RU 125362 Moscow Tel +7 495 787 78 21 aumarussia@auma.ru www.auma.ru

ERICHS ARMATUR AB SE 20039 Malmö Tel +46 40 311550 info@erichsarmatur.se www.erichsarmatur.se

ELSO-b, s.r.o. **SK 94901 Nitra** Tel +421 905/336-926 elsob@stonline.sk www.elsob.sk

Auma Endüstri Kontrol Sistemleri Limited Sirketi **TR 06810 Ankara** Tel +90 312 217 32 88 info@auma.com.tr

AUMA Technology Automations Ltd **UA 02099 Kiev** Tel +38 044 586-53-03 auma-tech@aumatech.com.ua

Africa

Solution Technique Contrôle Commande DZ Bir Mourad Rais, Algiers Tel +213 21 56 42 09/18 stcco@wissal.dz

A.T.E.C. **EG Cairo** Tel +20 2 23599680 - 23590861 contactus@atec-eg.com

SAMIREG MA 203000 Casablanca Tel +212 5 22 40 09 65 samireg@menara.ma

MANZ INCORPORATED LTD. **NG Port Harcourt** Tel +234-84-462741 mail@manzincorporated.com www.manzincorporated.com AUMA South Africa (Pty) Ltd. **ZA 1560 Springs** Tel +27 11 3632880 aumasa@mweb.co.za

America

AUMA Argentina Rep.Office **AR Buenos Aires** Tel +54 11 4737 9026 contacto@aumaargentina.com.ar

AUMA Automação do Brazil Itda. BR Sao Paulo Tel +55 11 4612-3477 contato@auma-br.com

TROY-ONTOR Inc. **CA L4N 8X1 Barrie, Ontario** Tel +1 705 721-8246 troy-ontor@troy-ontor.ca

AUMA Chile Representative Office **CL 9500414 Buin** Tel +56 2 821 4108 aumachile@auma-chile.cl

Ferrostaal de Colombia Ltda. **CO Bogotá D.C.** Tel +57 1 401 1300 dorian.hernandez@ferrostaal.com www.ferrostaal.com

AUMA Región Andina & Centroamérica EC Quito Tel +593 2 245 4614 auma@auma-ac.com www.auma.com

Corsusa International S.A.C. **PE Miraflores - Lima** Tel +511444-1200 / 0044 / 2321 corsusa@corsusa.com www.corsusa.com

Control Technologies Limited **TT Marabella, Trinidad, W.I.** Tel + 1 868 658 1744/5011 www.ctltech.com

AUMA ACTUATORS INC. US PA 15317 Canonsburg Tel +1 724-743-AUMA (2862) mailbox@auma-usa.com www.auma-usa.com

Suplibarca VE Maracaibo, Estado, Zulia Tel +58 261 7 555 667 suplibarca@intercable.net.ve

Asia

AUMA Actuators UAE Support Office **AE 287 Abu Dhabi** Tel +971 26338688 Nagaraj.Shetty@auma.com

AUMA Actuators Middle East BH 152 68 Salmabad Tel +97 3 17896585 salesme@auma.com Mikuni (B) Sdn. Bhd. BN KA1189 Kuala Belait Tel + 673 3331269 / 3331272 mikuni@brunet.bn

AUMA Actuators (China) Co., Ltd CN 215499 Taicang Tel +86 512 3302 6900 mailbox@auma-china.com www.auma-china.com

PERFECT CONTROLS Ltd. HK Tsuen Wan, Kowloon Tel +852 2493 7726 joeip@perfectcontrols.com.hk

PT. Carakamas Inti Alam ID 11460 Jakarta Tel +62 215607952-55 auma-jkt@indo.net.id

AUMA INDIA PRIVATE LIMITED. **IN 560 058 Bangalore** Tel +91 80 2839 4656 info@auma.co.in www.auma.co.in

ITG - Iranians Torque Generator IR 13998-34411 Teheran +982144545654 info@itg-co.ir

Trans-Jordan Electro Mechanical Supplies JO 11133 Amman Tel +962 - 6 - 5332020 Info@transjordan.net

AUMA JAPAN Co., Ltd. JP 211-0016 Kawasaki-shi, Kanagawa Tel +81-(0)44-863-8371 mailbox@auma.co.jp www.auma.co.jp

DW Controls Co., Ltd. **KR 153-702 Gasan-dong, GeumChun-Gu,, Seoul** Tel +82 2 2624 3400 import@actuatorbank.com www.actuatorbank.com

Al-Arfaj Engineering Co WLL **KW 22004 Salmiyah** Tel +965-24817448 info@arfajengg.com www.arfajengg.com

TOO "Armaturny Center" KZ 060005 Atyrau Tel +7 7122 454 602 armacentre@bk.ru

Network Engineering **LB 4501 7401 JBEIL, Beirut** Tel +961 9 944080 nabil.ibrahim@networkenglb.com www.networkenglb.com

AUMA Malaysia Office **MY 70300 Seremban, Negeri Sembilan** Tel +606 633 1988 sales@auma.com.my Mustafa Sultan Science & Industry Co LLC OM Ruwi Tel +968 24 636036 r-negi@mustafasultan.com

FLOWTORK TECHNOLOGIES CORPORATION PH 1550 Mandaluyong City Tel +63 2 532 4058 flowtork@pldtdsl.net

M & C Group of Companies **PK 54000 Cavalry Ground, Lahore Cantt** Tel +92 42 3665 0542, +92 42 3668 0118 sales@mcss.com.pk www.mcss.com.pk

Petrogulf W.L.L **QA Doha** Tel +974 44350151 pgulf@qatar.net.qa

AUMA Saudi Arabia Support Office SA 31952 AI Khobar Tel + 966 5 5359 6025 Vinod.Fernandes@auma.com

AUMA ACTUATORS (Singapore) Pte Ltd. SG 569551 Singapore Tel +65 6 4818750 sales@auma.com.sg www.auma.com.sg

NETWORK ENGINEERING SY Homs +963 31 231 571 eyad3@scs-net.org

Sunny Valves and Intertrade Corp. Ltd. **TH 10120 Yannawa, Bangkok** Tel +66 2 2400656 mainbox@sunnyvalves.co.th www.sunnyvalves.co.th

Top Advance Enterprises Ltd. **TW Jhonghe City, Taipei Hsien (235)** Tel +886 2 2225 1718 support@auma-taiwan.com.tw www.auma-taiwan.com.tw

AUMA Vietnam Hanoi RO VN Hanoi +84 4 37822115 chiennguyen@auma.com.vn

Australia

BARRON GJM Pty. Ltd. AU NSW 1570 Artarmon Tel +61 2 8437 4300 info@barron.com.au www.barron.com.au



AUMA Riester GmbH & Co. KG

P.O.Box 1362 **DE 79373 Muellheim** Tel +49 7631 809 - 0 Fax +49 7631 809 - 1250 riester@auma.com www.auma.com



Y003.822/003/en/1.15